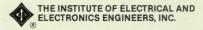
OMPUTER

CAD-BASED ROBOT VISION





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ARTICLES

Guest Editors' Introduction: CAD-Based Robot Vision

CAD-Based 3D Object Representation for Robot Vision

Bir Bhanu and Chih-Cheng Ho

Computer vision researchers lack a systematic approach for building object models for industrial environments. We propose a CAD-based approach for building representations and models for applications involving 3D object recognition and manipulation.

A CAD System Based on Spherical Dual Representations

John W. Roach, Praveen K. Paripati, and Jeffrey S. Wright

Most CAD systems for 3D modeling use geometric representations incompatible with vision technology. Here, a CAD system based on an extension of the Gaussian image, the spherical dual representation, preserves duality.

Prediction-Based Vision for Robot Control 46

Michael O. Shneier, Ronald Lumia, and Martin Herman

This sensing and control system employs a feedback loop to bring a robot's internal representation of its environment into registration with the real world.

Model-Based Strategy Planning for Recognizing Partially Occluded Parts

Radu Horaud and Thomas Skordas

Recognizing partially occluded objects requires off-line modeling and planning, and runtime recognition. After deriving a customized method, we can compare recognition with and without off-line planning.

CAD Model-Based Localization of Parts in Manufacturing

Kristjan T. Gunnarsson and Friedrich B. Prinz

We need automatic part localization in flexible manufacturing. One method of achieving it uses a CAD model and sparse data.

Model-Based Programming and Control of Robot Manipulators

Charles N. Stevenson

Multiple sensor systems and geometric object models can help a manipulation system adapt to uncertainty in its environment.

SPECIAL REPORT

The Effect of Abstract Data Types on Program Development

Jeffrey Mitchell, Joseph E. Urban, and Robert McDonald

An experiment demonstrated that using unsupported abstract data types increases program development time for novice programmers in an Ada environment.

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